

# MAXinBOX Hospitality v3 

## 2/4-Pipe Fan Coil Controller with <br> 2 Outputs and 6 Inputs with KNX Secure

## ZCLHP126V3

Application program version: [2.0]
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## DOCUMENT UPDATES

| Version | Changes | Page(s) |
| :---: | :---: | :---: |
|  | Changes in the application program: |  |
| $[2.0] \_a$ | Update of the shutters, master light, hospitality <br> thermostat and motion detector modules. | - |

## 1 INTRODUCTION

### 1.1 MAXinBOX Hospitality v3

MAXinBOX Hospitality v3 from Zennio is a versatile KNX multi-function actuator destined to cover the climate control needs in KNX environments with integrated fan coil units where both the fan speed and the opening of the water pipe valves are controlled by relays.

At a glance, the most outstanding features of MAXinBOX Hospitality v3 are:

- 2 multi-purpose relay outputs, configurable as:
> Up to two binary outputs.
> Up to one shutter channel.
Note: if a four-pipe fan coil with a three-point valve is configured, these two outputs are used to control the valve.
- 2 relay outputs to control one three-point valve or up to two on-off valves. One of these outputs can also be configured as an additional multipurpose relay output (in this case, for non-capacitive loads) in case it is not necessary for the fan coil control.
- 2 independent Hospitality Thermostats.
- 3 relay outputs to control up to three fan levels.
- 6 multi-purpose inputs, each of them configurable as:
> Temperature probe,
> Binary input (i.e., pushbuttons, switches, sensors),
> Motion detector
- 10 customisable, multi-operation logic functions.
- Master light control for an easy, out-of-the-box control of a set of luminaires (or functionally equivalent devices) one of which acts as a general lamp and the others as secondary lamps.
- Scene-triggered action control, with an optional delay in the execution.
- Manual operation / supervision of the relay outputs through the on-board pushbuttons and LEDs.
- Heartbeat or periodical "still-alive" notification.
- Relay Switches Counter.
- KNX Security.

For detailed information about the functionality and configuration of KNX security, consult the specific user manual "KNX Security Guide", available in the product section at www.zennio.com.

### 1.2 START-UP AND POWER LOSS

During the device start-up, the Prog./Test LED will blink in blue colour for a few seconds before MAXinBOX Hospitality v3 is ready. External orders will not be executed during this time, but afterwards.

Depending on the configuration, some specific actions will also be performed during the start-up. For example, the integrator can set whether the output channels should switch to a particular state and whether the device should send certain objects to the bus after the power recovery. Please consult the next sections of this document for further details.

On the other hand, when a bus power failure takes place, MAXinBOX Hospitality v3 will interrupt any pending actions, and will save its state so it can be recovered once the power supply is restored. In addition, the individual outputs will switch to the specific state configured in parameters.

For safety reasons, if a power loss takes place, all shutter channels will be stopped (i.e., the relays will open), while the individual outputs and fan coil contacts will switch to the specific state configured in ETS (if any).

### 1.3 STATUS INDICATORS

Each of the outputs of MAXinBOX Hospitality v3 incorporates a light indicator that reflects its current state.

### 1.3.1 BINARY AND SHUTTER OUTPUTS

If an output is configured as binary, the LED indicator will only be on while the relay remains closed; otherwise, it remains off.

If configured as a shutter channel, the LED indicator will only remain on while the shutter is in motion.

Please refer to section 2.3 for details about the relay outputs.

### 1.3.2 FAN COIL CONTROL OUTPUTS (VALVE / FAN)

Regarding the valve control outputs, the LED indicator of each output will behave analogously as the LEDs of the binary outputs: it will remain off while the corresponding valve is closed and on while the corresponding valve is open.

Regarding the fan control outputs, the two LED indicators provide information about the current fan speed level:

- Fan switched off: both LEDs off.
- Fan at speed level 1: both LEDs blinking every 1 second.
- Fan at speed level 2: both LEDs blinking every 0.5 seconds.
- Fan at speed level 3: both LEDs steadily on.

In case less than three different speed levels have been parameterised, the LEDs will stay steadily on while the fan is at the maximum level (e.g., level 2 ), and as described above for the lower levels (e.g., levels 1 and off).

Please refer to section 2.3 for details about the fan coil control outputs.

## 2 CONFIGURATION

### 2.1 GENERAL

After importing the corresponding database in ETS and adding the device into the topology of the desired project, the configuration process begins by entering the Parameters tab of the device.

## ETS PARAMETERISATION

From the "General" tab it is possible to mark/unmark the appropriate checkboxes to enable the required functionality. The only one active by default is "Manual Control" (see section 2.9), thus the corresponding tab will also be available from the beginning in the tab tree on the left.


Figure 1 General screen.

## - Scenes after Download [Keep Saved Scenes / Configured by Parameters] ${ }^{1}$ :

 allows defining whether the value of the scenes is the configured by parameter or whether the previously saved value is kept after download.Note: if "Keep Saved Scenes" option has been configured, but it is the first download of the device or a different version from the current one, the values configured by parameter will be adopted. If new scenes are added in

[^0]successive downloads, it will be necessary to perform a download by checking the option "Configured by Parameters" to ensure the correct operation of these scenes.

- Once activated, Inputs, Fan Coil, Thermostats, Outputs, Logic Functions, Master Light, Scene Timing and Manual Control bring additional tabs to the menu on the left (except for manual control, the rest are disabled by default). These functions and their parameters will be explained in later sections of this document.
- Heartbeat (Periodical Alive Notification) [disabled / enabled]: this parameter lets the integrator incorporate a one-bit object to the project ("[Heartbeat] Object to Send ' 1 '") that will be sent periodically with value " 1 " to notify that the device is still working (still alive).


Figure 2 Heartbeat (Periodical Alive Notification).

Note: the first sending after download or bus failure takes place with a delay of up to 255 seconds, to prevent bus overload. The following sendings match the period set.

- Device Recovery Objects (Send 0 and 1) [disabled / enabled]: this parameter lets the integrator activate two new communication objects ("[Heartbeat] Device Recovery"), which will be sent to the KNX bus with values " 0 " and " 1 " respectively whenever the device begins operation (for example, after a bus power failure). It is possible to parameterise a delay [0...255] for this sending.


Figure 3 Device Recovery Objects
Note: after download or bus failure, the sending takes place with a delay of up to 6,35 seconds plus the parameterised delay, to prevent bus overload.

- Show Relay Switches Counter Objects [disabled / enabled]: enables two communication objects to keep track of the number of switches performed by each of the relays ("[Relay X] Number of Switches") and the maximum number of switches carried out in a minute ("[Relay X] Maximum Switches per Minute").


### 2.2 INPUTS

MAXinBOX Hospitality v3 incorporates 6 analogue/digital inputs. Each one has three possible configurations, which are explained below.

### 2.2.1 BINARY INPUT

Configuration for the connection of a pushbutton or a switch/sensor. Please refer to the "Binary Inputs" user manual, available under the product section at www.zennio.com.

### 2.2.2 TEMPERATURE PROBE

Configuration for the connection of a temperature sensor from Zennio. Please refer to the "Temperature Probe" user manual, available under the product section at www.zennio.com.

### 2.2.3 MOTION DETECTOR

Configuration for the connection of a motion detector. It is possible to connect motion detectors from Zennio to the input ports of MAXinBOX 88 / 66 v 3.

Please refer to the "Motion Detector" user manual, available under the product section at www.zennio.com, for detailed information about the functionality and the configuration of the related parameters.

### 2.3 FAN COIL

MAXinBOX Hospitality v3 incorporates one fan coil control module, which will be responsible for operating the relays than open and close the water pipe valves (either one three-point valve or up to two on-off valves), and the relays that set the fan speed level. The latter can be achieved through relay accumulation (more relays closed means a higher fan speed) or through relay commutation (one specific relay will be available per level), depending on the configuration. The relays distribution for the valves control is shown in the following table for every possible parameterisation:

| Number of pipes | Valve type | Output | Action |
| :---: | :---: | :---: | :---: |
| 4 | On / Off | Output V1 | Cooling Valve |
|  |  | Heating Valve |  |
|  | Three-point | Output V1 | Opening Cooling Valve |
|  |  | Closing Cooling Valve |  |
|  |  | Opening Heating Valve |  |
| 2 | On / Off | Output 2 | Closing Heating Valve |
| 2 | Three-point | Cooling and/or Heating <br> Valve |  |
|  |  | Output V1 | Opening Valve for both <br> modes |
|  |  | Closing Valve for both <br> modes |  |

Table 1. Actions performed by the binary outputs associated to the valve control.
For a detailed description of these functions and on their configuration, please refer to the specific manual "Relays Fan Coil", available under the MAXinBOX Hospitality v3 product section at www.zennio.com.

### 2.4 HOSPITALITY THERMOSTAT

As described in previous sections, MAXinBOX Hospitality v3 includes two instances of the Hospitality Thermostat, which can be enabled and customized independently.

Please refer to the "Hospitality Thermostat" user manual, available under the MAXinBOX Hospitality v3 product section at www.zennio.com, for detailed information about the functionality and the configuration of the related parameters.

### 2.5 OUTPUTS

MAXinBOX Hospitality v3 incorporates two relay outputs, which can be configured in parameters as individual binary outputs to control up to two different loads, or as a joint shutter channel to control shutters and blinds, with or without slats.

Moreover, in case the fan coil module remains disabled (see section 2.3) or is configured to control a two-pipe fan coil unit consisting of a sole on-off valve, it is possible to configure one of the two valve control relay outputs (V2) as a third multipurpose binary output, although not valid to control capacitive loads.

## PARAMETERISATION

When the Outputs function has been activated in the "General" parameter screen, the "Outputs" section will be available in the tree on the left, containing itself a tab named "Configuration".


Figure 4 Outputs - Configuration.

Channel A can be configured through the drop-down list as two independent binary outputs or as a shutter channel (which makes use of both relays). Binary output V2 will also be available for configuration once the Fan Coil function has been disabled.

According to the above configuration, new entries will be incorporated into the tab tree.

For detailed information about the functionality and the configuration of the related parameters, please refer to the following specific manuals, available in the MAXinBOX Hospitality v3 product section at the Zennio homepage (www.zennio.com):

- Individual outputs.
- Shutter channels.


### 2.6 LOGIC FUNCTIONS

This module makes it possible to perform numeric and binary operations to incoming values received from the KNX bus, and to send the results through other communication objects specifically enabled for this purpose.

MAXinBOX Hospitality v3 allows enabling and fully customising up to ten different logic functions with their corresponding input objects, whose size can be 1 bit, 1 byte, 2 bytes or 4 bytes.

The execution of each function can depend on a configurable condition, which will be evaluated every time the function is triggered through specific, parameterisable communication objects. The result after executing the operations of the function can also be evaluated according to certain conditions and afterwards sent (or not) to the KNX bus, which can be done every time the function is executed, periodically or only when the result differs from the last one.

For detailed information about the functionality and the configuration of the related parameters, please refer to the specific manual "Logic Functions" available under the MAXinBOX Hospitality v3 product section at the www.zennio.com website.

### 2.7 MASTER LIGHT

The Master Light function brings the option to monitor the state of up to 30 light sources (or even more, if the Master Light controls from multiple Zennio devices are linked together) or of any other elements whose state is transmitted through a binary object and, depending on those states, perform a master order every time a certain trigger signal (again, a binary value) is received through a specific object.

Such master order will consist in:

- A general switch-off order, if at least one of the up to thirty status objects is on.
- A courtesy switch-on order, if none of the up to thirty status objects is on.

Note that the above switch-off and switch-on orders are not necessarily a binary value being sent to the bus - it is up to the integrator the decision of what to send to the KNX bus in both cases: a shutter order, a thermostat setpoint or mode switch order, a
constant value, a scene... Only the trigger object and the thirty status objects are required to be binary (on/off).

The most typical scenario for this Master Light control would be a hotel room with a master pushbutton next to the door. When leaving the room, the guest will have the possibility of pressing on the master pushbutton and make all the lamps turn off together. Afterwards, back on the room and with all the lamps off, pressing on the same master pushbutton will only make a particular lamp turn on (e.g., the closest lamp to the door) - this is the courtesy switch-on.

Besides, it is possible to concatenate two or more Master Light modules by means of a specific communication object which represents the general state of the light sources of each module. Thereby, it is possible to expand the number of light sources by considering the general state of one module as an additional light source for another.

## ETS PARAMETERISATION

Once the Master Light function has been enabled, a specific tab will be included in the menu on the left. This new parameter screen contains the following options:

| GENERAL | Number of State Objects | 1 | $\div$ |
| :---: | :---: | :---: | :---: |
| - Master Light | Trigger Value | 0/1 | $\checkmark$ |
| Configuration | General Switch Off |  |  |
| + Manual Control | Delay | 0 | $\times 1$ s |
|  | Binary Value | $\checkmark$ |  |
|  | Scaling |  |  |
|  | Scene |  |  |
|  | HVAC |  |  |
|  | Courtesy Switch On |  |  |
|  | Delay | 0 | $\stackrel{*}{\sim} 1 \mathrm{~s}$ |
|  | Binary Value | $\checkmark$ |  |
|  | Scaling |  |  |
|  | Scene |  |  |
|  | HVAC |  |  |

Figure 5 Master Light.

- Number of State Objects [1...30]: defines the number of 1-bit status objects required. These objects are called "[ML] Status Object $n$ ".

In addition, the general status object ("[ML] General status") will always be available in the project topology. It will be sent to the bus a " 1 " whenever
there is at least one of the above state objects with such value. Otherwise (i.e., if none of them has a value of " 1 "), it will be sent a " 0 ".

- Trigger Value [0/1/0/1]: sets the value that will trigger, when received through "[ML] Trigger", the master action (the general switch-off or the courtesy switch-on).


## - General Switch-Off.

> Delay [0...255]: defines a certain delay (once the trigger has been received) before the execution of the general switch-off.
> Binary Value [enabled / disabled]: if checked, the object "[ML] General Switch-off: Binary Object" will be enabled, which will send one " 0 " whenever the general switch-off takes off.
> Scaling [enabled / disabled]: if checked, the object "[ML] General Switchoff: Scaling" will be enabled, which will send a percentage value (configurable in "Value") whenever the general switch-off takes off.
> Scene [enabled / disabled]: if checked, the object "[ML] General Switchoff: Scene" will be enabled, which will send a scene run / save order (configurable in "Action" and "Scene Number") whenever the general switch-off takes off
> HVAC [enabled / disabled]: if checked, the object "[ML] General Switchoff: HVAC mode" will be enabled, which will send an HVAC thermostat mode value, configurable in "Value" [Auto / Comfort / Standby / Economy / Building Protection] whenever the general switch-off takes off.

Note: the above options are not mutually exclusive; it is possible to send values of different nature together.

## - Courtesy Switch-On:

The parameters available here are entirely analogous to those already mentioned for General Switch-Off. However, in this case the names of the objects start with "[ML] Courtesy Switch-On (...)". On the other hand, sending scene save orders is not possible for the courtesy switch-on (only orders to play scenes are allowed).

Note: object "[ML] Courtesy Switch-On: Binary Object" sends the value "1" (when the courtesy switch-on takes place), in contrast to object "[ML] General Switch-Off: Binary Object", which sends the value "0" (during the general switch-off, as explained above).

### 2.8 SCENE TIMING

The scene timing allows imposing delays over the scenes of the outputs. These delays are defined in parameters and can be applied to the execution of one or more scenes that may have been configured.

Pleas bear in mind that, as multiple delayed scenes can be configured for each individual output / shutter channel / fan coil module, in case of receiving an order of execute one of them when a previous temporisation is still pending for that output / channel / module, such temporisation will be interrupted and only the delay and the action of the new scene will be executed.

## ETS PARAMETRISATION

Prior to settings the scene timing, it is necessary to have one or more scenes configured in some of the outputs. When entering the Configuration window under "Scene Timing", all configured scenes will be listed, together with a few checkboxes to select which of them need to be temporised, as shown in the Figure 6.


Figure 6 Scene Timing.

Enabling a certain scene number n brings a new tab with such name to the menu on the left, from which it is possible to configure the temporisation of that scene for each of the outputs where it has been configured.


Figure 7 Scene Timing settings.
Therefore, parameter Scene Y. Output X Delay [0... 3600 [s] / 0... 1440 [min] / 0... 24 [ $h$ ] defines the delay that will be applied to the action defined in $X$ for the execution of scene $Y$ (where $X$ may be a specific individual output, shutter channel of fan coil module).

### 2.9 MANUAL CONTROL

MAXinBOX Hospitality v3 allows manually switching the state of its output relays through the respective pushbuttons on the top of the device. A specific pushbutton is therefore available per output.

Manual operation can be done in two different ways, named as Test On Mode (for testing purposes during the configuration of the device) and Test Off Mode (for a normal use, anytime). Whether both, only one, or none of these modes should be accessible needs to be parameterised in ETS. Moreover, it is possible to enable a specific binary object for locking and unlocking the manual control in runtime.

## Notes:

- The available control modes (Test On / Test Off) and the lock object can be enabled and disabled in MAXinBOX Hospitality v3 independently for the relay outputs (binary or shutter) and for the fan coil outputs (valves and fan).
- The Test Off mode will be active (unless it has been disabled by parameter) after a download or a reset with no need of a specific activation - the pushbuttons will respond to user presses from the start.
- On the contrary, switching to the Test On mode (unless disabled by parameter) needs to be done by long-pressing the Prog./Test button (for at least three seconds), until the LED is no longer red and turns yellow. From that moment, once the button is released, the LED light will remain green to confirm that the device has switched from the Test Off mode to the Test On mode. After that, an additional press will turn the LED yellow and then off, once the button is released. This way, the device leaves the Test On mode. Note that it will also leave this mode if a bus power failure takes place.
- This device is delivered from factory with the Test On and Test Off modes already enabled in parameters for all outputs.


## Test Off Mode

Under the Test Off Mode, the outputs can be controlled through both their communication objects and the actual pushbuttons located on the top of the device.

When one of these buttons is pressed, the output will behave as if an order had been received through the corresponding communication object, so it has no effect if the output is locked or under alarm status. The status objects of the different functions will still be sent in the usual way.

The action performed depends on the output type.

- Individual output: a simple press (short or long) will make the output (if enabled in parameters) switch its on-off state. This will be reported to the KNX bus through the corresponding status object, if enabled.
- Shutter channel: when the button is pressed, the device will act over the output according to the length of the button press and to the current state.
$>$ A long press makes the shutter start moving (upwards or downwards, depending on the button being pressed). The LED will light in green until the end of the motion. If the button gets pressed being the shutter already at the top or bottom positions, nothing will happen (the LED will not light).
> A short press will make the shutter drive stop (if in motion), as it normally does when a step/stop order is received from the KNX bus. In case of not being the shutter in motion, pressing the button does not cause any action, unless slats/lamellas have been parameterized - in such case, a step
movement (up/down, depending on the button pressed) will take place. The status objects will be sent to the bus when corresponding.
- Fan: a simple press (short or long) implies an increase or decrease of the fan speed (provided that the fan coil has been enabled in parameters), depending on the button pressed. This action will depend on the fan type (relay accumulation / relay commutation), the control type (cyclical or non-cyclical) and the minimum switch time configured. In particular:
> If the fan is already at the maximum speed level, a further increase will have no effect (in case of a non-cyclical control) or will switch back to the minimum level (in case of a cyclical control).
> If the fan is already at the minimum speed level, a further decrease will have no effect (in case of a non-cyclical control) or will switch back to the maximum level (in case of a cyclical control).
- Valve: a simple press (short or long) will make the valve switch its open/closed state, provided that the fan coil has been enabled in parameters. In case the fan coil control type has been configured in parameters as "applied to the fan" (instead of "applied to the valve"), this may also imply:
> A switch-on of the fan, if it is found to be stopped and the valve opens, provided that the desired fan speed is other than zero.
> A switch-off of the fan, it is found to be in motion and the valve closes, provided that the current mode is Heating (under Cooling, the fan will remain as is).
- Disabled output: outputs disabled in parameters will not react to button presses under the Test Off mode.

Regarding the lock, timer, alarm and scene functions, the device will behave as usual under the Test Off mode. Button presses during this mode are entirely analogous to the reception of the corresponding orders from the KNX bus.

## Test On Mode

After entering the Test On mode, it will only be possible to control the outputs through the on-board pushbuttons. Orders received through communication objects will be ignored, with independence of the output they are addressed to.

On the other hand, to prevent interference with the normal operation and since the Test On mode is intended for testing, once the device leaves the Test On mode it will switch back to its previous state.

Depending on the parameterisation of the output, the reactions to the button presses will differ.

- Individual outputs: short or long pressing the button will commute the on-off state of the relay.
- Shutter channel: pressing the button will make the shutter drive move upward or downward (depending on the button) until the button is released again, thus ignoring the position of the shutter and the parameterised times.

Note: after leaving the Test On mode, the status objects will recover the values they had prior to entering Test On. As the device is never aware of the actual position of the shutter (as the shutter drive does not provide any feedback), these values may not show the real position. This can be solved by performing a complete move-up or move-down order, or by calibrating the shutter position in the Test On mode until it matches the status objects.

- Fan: a simple press (short or long) implies an increase or decrease of the fan speed, depending on the button pressed.
> In case the fan coil module is disabled in parameters, it will work as noncyclical and through relay switching (with a 0.3 s delay).
> In any other case, the Test On mode will still respect the cyclical / noncyclical configuration, and the relay management type parameterised.
- Valves: a simple press (short or long) will make the valve switch its open/closed state. The behaviour is analogous as for the Test Off mode, although both valves will be controllable in Test On even if not enabled in parameters.
- Disabled outputs: under the Test On mode, short and long presses will cause the same effect for disabled outputs as for shutter channel outputs (i.e., the relay will switch its state until the button is released and only one relay per group is allowed to be closed).

The lock, timer, alarm and scene functions will not work while the device is under the Test On mode. Status objects will not be sent to the bus, either. However, alarms and lock orders received during the Test On mode will be taken into account once the device leaves this mode.

## ETS PARAMETERISATION

The Manual Control is configured from a specific tab which can be enabled from the "General" screen (see section 2.1).

| GENERAL | OUTPUTS MANUAL CONTROL |  |
| :---: | :--- | :--- |
| - Manual Control | Mode | Test Off Mode + Test On Mode |
| Configuration | Lock Manual Control? |  |
|  | FAN COIL MANUAL CONTROL |  |
|  | Mode | Test Off Mode + Test On Mode |

Figure 8 Manual Control.

The parameters available in this screen are grouped into two sections, as it is possible to configure independently the behaviour of the Manual Control for both, the fan coil and the individual binary outputs:

## - Mode: [Disabled / Only Test Mode Off / Only Test Mode On / Test Mode Off + Test Mode On].

Depending on the selection, the device will permit using the manual control under the Test Off, the Test On, or both modes. Note that, as stated before, using the Test Off mode does not require any special action, while switching to the Test On mode does require long-pressing the Prog./Test button.

- Lock Manual Control [enabled / disabled]: unless the above parameter has been set to disabled, enabling the Lock Manual Control parameter will provide a runtime procedure for locking the manual control. When this checkbox is enabled, object "Manual Control Lock" turns visible, as well as two more parameters:
> Value $[0=$ Lock; $1=$ Unlock $/ 0=$ Unlock; 1 = Lock]: defines whether the lock/unlock of the manual control should take place respectively upon the reception (through the aforementioned object) of values " 0 " and " 1 ", or the opposite.
> Initialisation [Unlocked / Locked / Last Value]: sets how the manual control should remain after the device start-up (after an ETS download or a bus power failure). "Last Value" on the first start-up will be unlocked.


## ANNEX I. COMMUNICATION OBJECTS

- "Functional range" shows the values that, with independence of any other values permitted by the bus according to the object size, may be of any use or have a particular meaning because of the specifications or restrictions from both the KNX standard or the application program itself.

| Number | Size | I/O | Flags | Data type (DPT) | Functional Range | Name | Function |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | 1 Bit | I | C - W - - | DPT_Enable | 0/1 | Lock Manual Control (Outputs) | 0 = Lock; 1 = Unlock |
|  | 1 Bit | I | C-W - - | DPT_Enable | 0/1 | Lock Manual Control (Outputs) | 0 = Unlock; 1 = Lock |
| 2 | 1 Bit | I | C-W - - | DPT_Enable | 0/1 | Lock Manual Control (Fan Coil) | 0 = Unlock; 1 = Lock |
|  | 1 Bit | I | C - W - - | DPT_Enable | 0/1 | Lock Manual Control (Fan Coil) | 0 = Lock; 1 = Unlock |
| 3,5 | 4 Bytes | 0 | C R - - - | DPT_Value_4_Ucount | 0-4294967295 | [Relay Ox] Number of Switches | Number of Switches |
| 4,6 | 2 Bytes | 0 | C R - - | DPT_Value_2_Ucount | 0-65535 | [Relay Ox] Maximum Switches per Minute | Maximum Switches per Minute |
| 7,15 | 4 Bytes | 0 | C R - - - | DPT_Value_4_Ucount | 0-4294967295 | [Relay Vx] Number of Switches | Number of Switches |
| 8,16 | 2 Bytes | 0 | C R - - | DPT_Value_2_Ucount | 0-65535 | [Relay Vx] Maximum Switches per Minute | Maximum Switches per Minute |
| 9, 11, 13 | 4 Bytes | 0 | C R - - - | DPT_Value_4_Ucount | 0-4294967295 | [Relay Fx] Number of Switches | Number of Switches |
| 10, 12, 14 | 2 Bytes | 0 | C R - - | DPT_Value_2_Ucount | 0-65535 | [Relay Fx] Maximum Switches per Minute | Maximum Switches per Minute |
| 17, 23, 29, 35, 41, 47 | 1 Bit | I | C-W - - | DPT_Enable | 0/1 | [Ix] Input Lock | 0 = Unlock; 1 = Lock |
| 18, 24, 30, 36, 42,48 | 1 Bit |  | C - - T - | DPT_Switch | 0/1 | [Ix] [Short Press] 0 | Sending of 0 |
|  | 1 Bit |  | C - - T - | DPT_Switch | 0/1 | [Ix] [Short Press] 1 | Sending of 1 |
|  | 1 Bit | I | C - W T - | DPT_Switch | 0/1 | [Ix] [Short Press] 0/1 Switching | Switching 0/1 |
|  | 1 Bit |  | C-- T- | DPT_UpDown | 0/1 | [Ix] [Short Press] Move Up Shutter | Sending of 0 (Up) |
|  | 1 Bit |  | C - - ${ }^{\text {- }}$ | DPT_UpDown | 0/1 | [Ix] [Short Press] Move Down Shutter | Sending of 1 (Down) |
|  | 1 Bit |  | C-- T- | DPT_UpDown | 0/1 | [Ix] [Short Press] Move Up/Down Shutter | Switching 0/1 (Up/Down) |
|  | 1 Bit |  | C - - ${ }^{\text {- }}$ | DPT_Step | 0/1 | [Ix] [Short Press] Stop/Step Up Shutter | Sending of 0 (Stop/Step Up) |
|  | 1 Bit |  | C-- T- | DPT_Step | 0/1 | [Ix] [Short Press] Stop/Step Down Shutter | Sending of 1 (Stop/Step Down) |
|  | 1 Bit |  | C-- T- | DPT_Step | 0/1 | [Ix] [Short Press] Stop/Step Shutter (Switched) | Switching of 0/1 (Stop/Step Up/Down) |
|  | 4 Bit |  | C-- T- | DPT_Control_Dimming | $0 \times 0 / 0 \times 8$ (Stop) $0 \times 1 . .0 \times 7$ (Dec.) 0x9...0xF (Inc.) | [Ix] [Short Press] Brighter | Increase Brightness |
|  | 4 Bit |  | C-- T- | DPT_Control_Dimming | 0x0/0x8 (Stop) <br> $0 \times 1 . . .0 \times 7$ (Dec.) 0x9...0xF (Inc.) | [Ix] [Short Press] Darker | Decrease Brightness |


|  | 4 Bit |  | C-- T- | DPT_Control_Dimming | 0x0/0x8 (Stop) $0 \times 1 . . .0 \times 7$ (Dec.) $0 \times 9 \ldots 0 \times F$ (Inc.) | [Ix] [Short Press] Brighter/Darker | Switch Bright/Dark |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1 Bit |  | C - - T - | DPT_Switch | 0/1 | [Ix] [Short Press] Light On | Sending of 1 (On) |
|  | 1 Bit |  | C-- T- | DPT_Switch | 0/1 | [Ix] [Short Press] Light Off | Sending of 0 (Off) |
|  | 1 Bit | I | C - W T - | DPT_Switch | 0/1 | [Ix] [Short Press] Light On/Off | Switching 0/1 |
|  | 1 Byte |  | C - - T - | DPT_SceneControl | 0-63; 128-191 | [Ix] [Short Press] Run Scene | Sending of 0-63 |
|  | 1 Byte |  | C - - T - | DPT_SceneControl | 0-63; 128-191 | [Ix] [Short Press] Save Scene | Sending of 128-191 |
|  | 1 Bit | I/O | C R W T - | DPT_Switch | 0/1 | [Ix] [Switch/Sensor] Edge | Sending of 0 or 1 |
|  | 1 Byte |  | C - - ${ }^{\text {- }}$ | DPT_Value_1_Ucount | 0-255 | [Ix] [Short Press] Constant Value (Integer) | 0-255 |
|  | 1 Byte |  | C-- T- | DPT_Scaling | 0\%-100\% | [Ix] [Short Press] Constant Value (Percentage) | 0\% - 100\% |
|  | 2 Bytes |  | C - - ${ }^{\text {- }}$ | DPT_Value_2_Ucount | 0-65535 | [Ix] [Short Press] Constant Value (Integer) | 0-65535 |
|  | 2 Bytes |  | C - - ${ }^{\text {- }}$ | 9.xxx | -671088.64-670433.28 | [Ix] [Short Press] Constant Value (Float) | Float Value |
|  | 2 Bytes | 0 | C R - T - | DPT_Value_2_Ucount | 0-65535 | [Ix] [Pulse Counter] Counter | Number of Pulses |
| 19, 25, 31, 37, 43, 49 | 1 Byte | I | C - W - - | DPT_Scaling | 0\%-100\% | [Ix] [Short Press] Shutter Status (Input) | 0\% = Top; 100\% = Bottom |
|  | 1 Byte | I | C - W - - | DPT_Scaling | 0\%-100\% | [Ix] [Short Press] Dimming Status (Input) | 0\%-100\% |
|  | 1 Byte | 0 | C R - T - | DPT_Value_1_Ucount | 0-255 | [Ix] [Pulse Counter] Counter | Number of Pulses |
| 20, 26, 32, 38, 44, 50 | 1 Bit |  | $\mathrm{C}-$ - T- | DPT_Switch | 0/1 | [Ix] [Long Press] 0 | Sending of 0 |
|  | 1 Bit |  | C - - T - | DPT_Switch | 0/1 | [Ix] [Long Press] 1 | Sending of 1 |
|  | 1 Bit | I | C - W T - | DPT_Switch | 0/1 | [Ix] [Long Press] 0/1 Switching | Switching 0/1 |
|  | 1 Bit |  | C-- T- | DPT_UpDown | 0/1 | [Ix] [Long Press] Move Up Shutter | Sending of 0 (Up) |
|  | 1 Bit |  | C-- T- | DPT_UpDown | 0/1 | [Ix] [Long Press] Move Down Shutter | Sending of 1 (Down) |
|  | 1 Bit |  | C - - ${ }^{\text {- }}$ | DPT_UpDown | 0/1 | [Ix] [Long Press] Move Up/Down Shutter | Switching 0/1 (Up/Down) |
|  | 1 Bit |  | C-- T- | DPT_Step | 0/1 | [Ix] [Long Press] Stop/Step Up Shutter | Sending of 0 (Stop/Step Up) |
|  | 1 Bit |  | C-- T- | DPT_Step | 0/1 | [Ix] [Long Press] Stop/Step Down Shutter | Sending of 1 (Stop/Step Down) |
|  | 1 Bit |  | C-- T- | DPT_Step | 0/1 | $\begin{aligned} & \text { [Ix] [Long Press] Stop/Step Shutter } \\ & \text { (Switched) } \end{aligned}$ | Switching of 0/1 (Stop/Step Up/Down) |
|  | 4 Bit |  | C-- T- | DPT_Control_Dimming | $\begin{aligned} & 0 \times 0 / 0 \times 8 \text { (Stop) } \\ & 0 \times 1 \ldots 0 \times 7 \text { (Dec.) } \\ & 0 \times 9 \ldots 0 \times F \text { (Inc.) } \end{aligned}$ | [Ix] [Long Press] Brighter | Long Pr. -> Brighter; Release -> Stop |
|  | 4 Bit |  | C-- T- | DPT_Control_Dimming | 0x0/0x8 (Stop) $0 \times 1 . . .0 \times 7$ (Dec.) 0x9...0xF (Inc.) | [Ix] [Long Press] Darker | Long Pr. -> Darker; Release -> Stop |


|  | 4 Bit |  | C-- T- | DPT_Control_Dimming | 0x0/0x8 (Stop) 0x1...0x7 (Dec.) $0 \times 9 . .0 \times \mathrm{F}$ (Inc.) | [Ix] [Long Press] Brighter/Darker | Long Pr. -> Brighter/Darker; Release -> Stop |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1 Bit |  | C-- T- | DPT_Switch | 0/1 | [Ix] [Long Press] Light On | Sending of 1 (On) |
|  | 1 Bit |  | C - - T- | DPT_Switch | 0/1 | [Ix] [Long Press] Light Off | Sending of 0 (Off) |
|  | 1 Bit | I | C - W T - | DPT_Switch | 0/1 | [Ix] [Long Press] Light On/Off | Switching 0/1 |
|  | 1 Byte |  | C - - T- | DPT_SceneControl | 0-63; 128-191 | [Ix] [Long Press] Run Scene | Sending of 0-63 |
|  | 1 Byte |  | C-- T- | DPT_SceneControl | 0-63; 128-191 | [Ix] [Long Press] Save Scene | Sending of 128-191 |
|  | 1 Bit | 0 | C R - T - | DPT_Alarm | 0/1 | [Ix] [Switch/Sensor] Alarm: Breakdown or Sabotage | 1 = Alarm; $0=$ No Alarm |
|  | 2 Bytes |  | C - - ${ }^{\text {- }}$ | 9.xxx | -671088.64-670433.28 | [Ix] [Long Press] Constant Value (Float) | Float Value |
|  | 2 Bytes |  | C - - ${ }^{\text {- }}$ | DPT_Value_2_Ucount | 0-65535 | [Ix] [Long Press] Constant Value (Integer) | 0-65535 |
|  | 1 Byte |  | C - - ${ }^{\text {- }}$ | DPT_Scaling | 0\%-100\% | [Ix] [Long Press] Constant Value (Percentage) | 0\% - 100\% |
|  | 1 Byte |  | C-- T- | DPT_Value_1_Ucount | 0-255 | [Ix] [Long Press] Constant Value (Integer) | 0-255 |
|  | 1 Bit |  | C - - T- | DPT_Switch | 0/1 | [Ix] [Double Press] 0 | Sending of 0 |
|  | 1 Bit |  | $\mathrm{C}-\mathrm{-T}$ - | DPT_Switch | 0/1 | [Ix] [Double Press] 1 | Sending of 1 |
|  | 1 Bit | I | C - W T - | DPT_Switch | 0/1 | [Ix] [Double Press] 0/1 Switching | Switching 0/1 |
|  | 1 Byte |  | C-- T- | DPT_SceneControl | 0-63; 128-191 | [Ix] [Double Press] Save Scene | Sending of 128-191 |
|  | 1 Byte |  | C - - T - | DPT_SceneControl | 0-63; 128-191 | [Ix] [Double Press] Run Scene | Sending of 0-63 |
| 21, 27, 33, 39, 45, 51 | 1 Bit |  | C-- T - | DPT_Trigger | 0/1 | [Ix] [Long Press/Release] Stop Shutter | Release -> Stop Shutter |
|  | 1 Bit | I | C-W - - | DPT_Reset | 0/1 | [Ix] [Pulse Counter] Reset | 0 = No Action; 1 = Reset |
|  | 1 Byte | I | C-W -- | DPT_Scaling | 0\%-100\% | [Ix] [Long Press] Dimming Status (Input) | 0\% - 100\% |
|  | 1 Byte | I | C-W-- | DPT_Scaling | 0\%-100\% | [Ix] [Long Press] Shutter Status (Input) | 0\% = Top; 100\% = Bottom |
| 53 | 1 Byte | I | C-W - - | DPT_SceneNumber | 0-63 | [Motion Detector] Scene Input | Scene Value |
| 54 | 1 Byte |  | C - - T- | DPT_SceneControl | 0-63; 128-191 | [Motion Detector] Scene Output | Scene Value |
| 55, 89, 123, 157, 191, 225 | 1 Byte | 0 | C R - T - | DPT_Scaling | 0\%-100\% | [Ix] Luminosity | 0-100\% |
| 56, 90, 124, 158, 192, 226 | 1 Bit | 0 | C R - T - | DPT_Alarm | 0/1 | [Ix] Open Circuit Error | 0 = No Error; 1 = Open Circuit Error |
| 57, 91, 125, 159, 193, 227 | 1 Bit | 0 | C R - T - | DPT_Alarm | 0/1 | [Ix] Short Circuit Error | 0 = No Error; 1 = Short Circuit Error |
| 58, 92, 126, 160, 194, 228 | 1 Byte | 0 | C R - T - | DPT_Scaling | 0\%-100\% | [Ix] Presence State (Scaling) | 0-100\% |
| 59, 93, 127, 161, 195, 229 | 1 Byte | 0 | C R - T - | DPT_HVACMode | 1=Comfort <br> 2=Standby <br> 3=Economy <br> 4 =Building <br> Protection | [Ix] Presence State (HVAC) | Auto, Comfort, Standby, Economy, Building Protection |
| 60, 94, 128, 162, 196, 230 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [Ix] Presence State (Binary) | Binary Value |
|  | 1 Bit | 0 | C R - T - | DPT_Start | 0/1 | [Ix] Presence: Slave Output | 1 = Motion Detected |


| 61, 95, 129, 163, 197, 231 | 1 Bit | I | C - W - - | DPT_Window_Door | 0/1 | [Ix] Presence Trigger | Binary Value to Trigger the Presence Detection |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 62, 96, 130, 164, 198, 232 | 1 Bit | I | C - W - - | DPT_Start | 0/1 | [Ix] Presence: Slave Input | $0=$ Nothing; $1=$ Detection from slave device |
| 63, 97, 131, 165, 199, 233 | 2 Bytes | I/O | C R W - - | DPT_TimePeriodSec | 0-65535 | [Ix] Presence: Waiting Time | 0-65535 s. |
| 64, 98, 132, 166, 200, 234 | 2 Bytes | I/O | C R W - - | DPT_TimePeriodSec | 0-65535 | [Ix] Presence: Listening Time | $1-65535 \mathrm{~s}$. |
| 65, 99, 133, 167, 201, 235 | 2 Bytes | I/O | C R W - - | DPT_TimePeriodMin | 0-65535 | [Ix] Presence: Safety Time | 0-1440 min. |
| 66, 100, 134, 168, 202, 236 | 1 Byte | I/O | C R W -- | DPT_Value_1_Ucount | 0-255 | [Ix] Presence: Filter Detections Number | 2-5 |
| 67, 101, 135, 169, 203, 237 | 1 Byte | I/O | C R W -- | DPT_Value_1_Ucount | 0-255 | [Ix] Presence: Filter Detection Window | 15-60 s. |
| 68, 102, 136, 170, 204, 238 | 1 Bit | I | C - W - - | DPT_Enable | 0/1 | [Ix] Presence: Enable | According to parameters |
| 69, 103, 137, 171, 205, 239 | 1 Bit | I/O | C R W - - | DPT_DayNight | 0/1 | [Ix] Presence: Day/Night | According to parameters |
| 70, 104, 138, 172, 206, 240 | 1 Bit | 0 | C R - T - | DPT_Occupancy | 0/1 | [Ix] Presence: Occupancy State (Master Output) | $0=$ Not Occupied; 1 = Occupied |
|  | 1 Bit | I | C - W - - | DPT_Occupancy | 0/1 | [Ix] Presence: Occupancy State (Master Input) | $0=$ Not Occupied; $1=$ Occupied |
| 71, 105, 139, 173, 207, 241 | 1 Bit | I | C - W - - | DPT_Switch | 0/1 | [Ix] Presence: Access Guest/Employee | 0 = Guest; 1 = Employee |
|  | 1 Bit | I | C - W - - | DPT_Switch | 0/1 | [Ix] Presence: Access Guest/Employee | 0 = Employee; 1 = Guest |
| 72, 106, 140, 174, 208, 242 | 1 Bit | I | C-W - - | DPT_Bool | 0/1 | [Ix] Presence: Sold/Unsold Room | 0 = Unsold; 1 = Sold |
|  | 1 Bit | I | C - W - - | DPT_Bool | 0/1 | [Ix] Presence: Sold/Unsold Room | 0 = Sold; 1 = Unsold |
| 73, 107, 141, 175, 209, 243 | 1 Bit | I | C - W - - | DPT_Start | 0/1 | [Ix] External Motion Detection | $0=$ Nothing; $1=$ Motion detected by an external sensor |
| $\begin{gathered} \hline 74,79,84,108,113,118, \\ 142,147,152,176,181, \\ 186,210,215,220,244, \\ 249,254 \\ \hline \end{gathered}$ | 1 Byte | 0 | C R-T- | DPT_Scaling | 0\% - 100\% | [Ix] [Cx] Detection State (Scaling) | 0-100\% |
| $\begin{gathered} 75,80,85,109,114,119, \\ 143,148,153,177,182, \\ 187,211,216,221,245, \\ 250,255 \end{gathered}$ | 1 Byte | 0 | C R - T - | DPT_HVACMode | 1 = Comfort <br> 2=Standby <br> 3=Economy <br> 4=Building <br> Protection | [Ix] [Cx] Detection State (HVAC) | Auto, Comfort, Standby, Economy, Building Protection |
| $\begin{gathered} \hline 76,81,86,110,115,120, \\ 144,149,154,178,183, \\ 188,212,217,222,246, \\ 251,256 \\ \hline \end{gathered}$ | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [Ix] [Cx] Detection State (Binary) | Binary Value |
| $\begin{gathered} \hline 77,82,87,111,116,121, \\ 145,150,155,179,184, \\ 189,213,218,223,247, \\ 252,257 \\ \hline \end{gathered}$ | 1 Bit | I | C-W-- | DPT_Enable | 0/1 | [Ix] [Cx] Enable Channel | According to parameters |
| $\begin{gathered} \hline 78,83,88,112,117,122, \\ 146,151,156,180,185, \\ 190,214,219,224,248, \\ 253,258 \\ \hline \end{gathered}$ | 1 Bit | I | C-W-- | DPT_Switch | 0/1 | [Ix] [Cx] Force State | $0=$ No Detection; 1 = Detection |


| $\begin{gathered} \text { 259, 263, 267, 271, 275, } \\ 279 \end{gathered}$ | 2 Bytes | 0 | C R - T - | DPT_Value_Temp | -273.000 - 670433.280 | [Ix] Current Temperature | Temperature Sensor Value |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{gathered} \hline 260,264,268,272,276, \\ 280 \end{gathered}$ | 1 Bit | 0 | C R - T - | DPT_Alarm | 0/1 | [Ix] Overcooling | 0 = No Alarm; 1 = Alarm |
| $\begin{gathered} \hline 261,265,269,273,277, \\ 281 \end{gathered}$ | 1 Bit | 0 | C R - T - | DPT_Alarm | 0/1 | [Ix] Overheating | 0 = No Alarm; 1 = Alarm |
| $\begin{gathered} \hline 262,266,270,274,278, \\ 282 \\ \hline \end{gathered}$ | 1 Bit | 0 | C R - T - | DPT_Alarm | 0/1 | [Ix] Probe Error | 0 = No Alarm; 1 = Alarm |
| 283 | 1 Byte | I | C - W - - | DPT_SceneControl | 0-63; 128-191 | [Ox] Scenes | $\begin{aligned} & 0-63 \text { (Execute } 1-64 \text { ); } 128-191 \\ & \text { (Save } 1-64 \text { ) } \end{aligned}$ |
| 284 | 1 Bit | I | C - W - - | DPT_BinaryValue | 0/1 | [Ox] On/Off | N.O. (0 = Open Relay; 1 = Close Relay) |
|  | 1 Bit | I | C - W - - | DPT_BinaryValue | 0/1 | [Ox] On/Off | N.C. (0=Close Relay; 1= Open Relay) |
| 285 | 1 Bit | 0 | C R - T - | DPT_BinaryValue | 0/1 | [Ox] On/Off (Status) | 0 = Output Off; 1 = Output On |
| 286 | 1 Bit | I | C - W - - | DPT_Enable | 0/1 | [Ox] Lock | 0 = Unlock; 1 = Lock |
| 287 | 1 Bit | I | C - W - - | DPT_Start | 0/1 | [Ox] Timer | 0 = Switch Off; 1 = Switch On |
| 288 | 1 Bit | I | C - W - - | DPT_Start | 0/1 | [Ox] Flashing | 0 = Stop; 1 = Start |
| 289 | 1 Bit | I | C - W - - | DPT_Alarm | 0/1 | [Ox] Alarm | 0 = Normal; 1 = Alarm |
|  | 1 Bit | I | C - W - - | DPT_Alarm | 0/1 | [Ox] Alarm | 0=Alarm; 1 = Normal |
| 290 | 1 Bit | I | C - W - - | DPT_Ack | 0/1 | [Ox] Unfreeze Alarm | Alarm $=0$ + Unfreeze = 1 => End Alarm |
| 291 | 1 Bit | 0 | C R - T - | DPT_State | 0/1 | [Ox] Warning Time (Status) | 0 = Normal; 1 = Warning |
| 292 | 4 Bytes | I/O | C R W T - | DPT_LongDeltaTimeSec | $\begin{array}{r} -2147483648 \\ 2147483647 \\ \hline \end{array}$ | [Ox] Operating Time (s) | Time in Seconds |
| 293 | 2 Bytes | I/O | C R W T - | DPT_TimePeriodHrs | 0-65535 | [Ox] Operating Time (h) | Time in Hours |
| 316 | 1 Byte | I | C - W - - | DPT_SceneControl | 0-63; 128-191 | [Shutter] Scenes | $\begin{aligned} & \text { 0-63 (Execute } 1-64) ; 128-191 \\ & \text { (Save 1-64) } \end{aligned}$ |
| 317 | 1 Bit | I | C-W - - | DPT_UpDown | 0/1 | [Cx] Move | 0 = Raise; 1 = Lower |
| 318 | 1 Bit | I | C - W - - | DPT_Step | 0/1 | [Cx] Stop/Step | 0 = Stop/StepUp; 1 = Stop/StepDown |
|  | 1 Bit | I | C-W - - | DPT_Trigger | 0/1 | [Cx] Stop | 0 = Stop; 1 = Stop |
| 319 | 1 Bit | I | C - W - - | DPT_Trigger | 0/1 | [Cx] Switched Control | 0,1 = Up, Down or Stop, Depending on the Last Move |
| 320 | 1 Bit | I | C - W - - | DPT_Trigger | 0/1 | [Cx] Switched Control Up | $0,1=$ Up or Stop, Depending on the Last Move |
| 321 | 1 Bit | I | C - W - - | DPT_Trigger | 0/1 | [Cx] Switched Control Down | 0,1 = Down or Stop, Depending on the Last Move |
| 322 | 1 Bit | I | C - W - - | DPT_Enable | 0/1 | [Cx] Lock | 0 = Unlock; 1 = Lock |
| 323 | 1 Byte | I | C - W - - | DPT_Scaling | 0\%-100\% | [Cx] Shutter Positioning | 0\% = Top; 100\% = Bottom |
| 324 | 1 Byte | 0 | C R - T - | DPT_Scaling | 0\% - 100\% | [Cx] Shutter Position (Status) | 0\% = Top; 100\% = Bottom |
| 325 | 1 Byte | I | C - W - - | DPT_Scaling | 0\% - 100\% | [Cx] Slats Positioning | 0\% = Open; 100\% = Closed |
| 326 | 1 Byte | 0 | C R - T - | DPT_Scaling | 0\% - 100\% | [Cx] Slats Position (Status) | 0\% = Open; 100\% = Closed |
| 327 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [Cx] Rising Relay (Status) | 0 = Open; 1 = Closed |
| 328 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [Cx] Lowering Relay (Status) | 0 = Open; 1 = Closed |


| 329 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [Cx] Movement (Status) | 0 = Stopped; 1 = Moving |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 330 | 1 Bit | 0 | C R - T - | DPT_UpDown | 0/1 | [Cx] Movement Direction (Status) | 0 = Upward; 1 = Downward |
| 331 | 1 Bit | I | C - W - - | DPT_Switch | 0/1 | [Cx] Auto: On/Off | $0=$ On; $1=$ Off |
|  | 1 Bit | I | C - W - - | DPT_Switch | 0/1 | [Cx] Auto: On/Off | 0 = Off; 1 = On |
| 332 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [Cx] Auto: On/Off (Status) | $0=$ On; 1 = Off |
|  | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [Cx] Auto: On/Off (Status) | $0=$ Off; 1 = On |
| 333 | 1 Bit | I | C - W - - | DPT_UpDown | 0/1 | [Cx] Auto: Move | 0 = Raise; 1 = Lower |
| 334 | 1 Bit | I | C - W - - | DPT_Step | 0/1 | [Cx] Auto: Stop/Step | 0 = Stop/StepUp; 1 = Stop/StepDown |
|  | 1 Bit | I | C - W - - | DPT_Trigger | 0/1 | [Cx] Auto: Stop | 0 = Stop; 1 = Stop |
| 335 | 1 Byte | I | C - W - - | DPT_Scaling | 0\%-100\% | [Cx] Auto: Shutter Positioning | 0\% = Top; 100\% = Bottom |
| 336 | 1 Byte | I | C-W - - | DPT_Scaling | 0\% - 100\% | [Cx] Auto: Slats Positioning | 0\% = Open; 100\% = Closed |
| 337 | 1 Bit | I | C-W T U | DPT_Scene_AB | 0/1 | [Cx] Sunshine/Shadow | 0 = Sunshine; 1 = Shadow |
|  | 1 Bit | I | C-W T U | DPT_Scene_AB | 0/1 | [Cx] Sunshine/Shadow | 0 = Shadow; 1 = Sunshine |
| 338 | 1 Bit | I | C-W T U | DPT_Heat_Cool | 0/1 | [Cx] Cooling/Heating | $0=$ Cooling; $1=$ Heating |
|  | 1 Bit | I | C-W T U | DPT_Heat_Cool | 0/1 | [Cx] Cooling/Heating | $0=$ Heating; $1=$ Cooling |
| 339 | 1 Bit | I | C-W T U | DPT_Occupancy | 0/1 | [Cx] Presence/No Presence | 0 = No Presence; 1 = Presence |
|  | 1 Bit | I | C-W T U | DPT_Occupancy | 0/1 | [Cx] Presence/No Presence | 0 = Presence; 1 = No Presence |
| 340, 341 | 1 Bit | I | C - W - - | DPT_Alarm | 0/1 | [Cx] Alarm x | 0 = No Alarm; 1 = Alarm |
|  | 1 Bit | I | C - W - - | DPT_Alarm | 0/1 | [Cx] Alarm $x$ | 0 = Alarm; 1 = No Alarm |
| 342 | 1 Bit | I | C-W-- | DPT_Ack | 0/1 | [Cx] Unfreeze Alarm | Alarm1 = Alarm2 = No Alarm + Unfreeze (1) => End Alarm |
| 343 | 1 Bit | I | C - W - - | DPT_Scene_AB | 0/1 | [Cx] Move (Reversed) | 0 = Lower; 1 = Raise |
| 344 | 1 Bit | I | C - W - - | DPT_Ack | 0/1 | [Cx] Direct Positioning 1 | $0=$ No Action; $1=$ Go to Position |
| 345 | 1 Bit | I | C - W - - | DPT_Ack | 0/1 | [Cx] Direct Positioning 2 | 0 = No Action; 1 = Go to Position |
| 346 | 1 Bit | I | C - W - - | DPT_Ack | 0/1 | [Cx] Direct Positioning 1 (Save) | $0 \text { = No Action; } 1 \text { = Save Current }$ Position |
| 347 | 1 Bit | I | C - W - - | DPT_Ack | 0/1 | [Cx] Direct Positioning 2 (Save) | $\begin{array}{\|l} \hline 0=\text { No Action; } 1 \text { = Save Current } \\ \text { Position } \end{array}$ |
| 348 | 1 Bit | 0 | C R - T - | DPT_BinaryValue | 0/1 | [Cx] External Contact - Stop Movement | 0 = Open Relay; 1 = Close Relay |
| 349, 350, 351, 352, 353, 354, 355, 356, 357, 358, 359, 360, 361, 362, 363, $364,365,366,367,368$, $369,370,371,372,373$, $374,375,376,377,378$, 379,380 | 1 Bit | I | C-W-- | DPT_Bool | 0/1 | [LF] (1-Bit) Data Entry x | Binary Data Entry (0/1) |
| $\begin{gathered} \text { 381, 382, 383, 384, 385, } \\ 386,387,388,389,390, \\ 391,392,393,394,395, \\ 396 \end{gathered}$ | 1 Byte | I | C-W-- | DPT_Value_1_Ucount | 0-255 | [LF] (1-Byte) Data Entry x | 1-Byte Data Entry (0-255) |
| 397, 398, 399, 400, 401, | 2 Bytes | I | C - W - - | DPT_Value_2_Ucount | 0-65535 | [LF] (2-Byte) Data Entry x | 2-Byte Data Entry |
| 402, 403, 404, 405, 406, | 2 Bytes | I | C - W - - | DPT_Value_2_Count | -32768-32767 | [LF] (2-Byte) Data Entry x | 2-Byte Data Entry |


| $\begin{gathered} 407,408,409,410,411, \\ 412 \end{gathered}$ | 2 Bytes | I | C-W-- | 9.xxx | -671088.64-670433.28 | [LF] (2-Byte) Data Entry x | 2-Byte Data Entry |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{gathered} 413,414,415,416,417 \\ 418,419,420 \\ \hline \end{gathered}$ | 4 Bytes | I | C-W-- | DPT_Value_4_Count | $\begin{array}{r} -2147483648 \\ 2147483647 \\ \hline \end{array}$ | [LF] (4-Byte) Data Entry x | 4-Byte Data Entry |
| $\begin{aligned} & 421,422,423,424,425 \\ & 426,427,428,429,430 \end{aligned}$ | 1 Bit | 0 | C R - T - | DPT_Bool | 0/1 | [LF] Function x - Result | (1-Bit) Boolean |
|  | 1 Byte | 0 | C R - T - | DPT_Value_1_Ucount | 0-255 | [LF] Function x - Result | (1-Byte) Unsigned |
|  | 2 Bytes | 0 | C R - T - | DPT_Value_2_Ucount | 0-65535 | [LF] Function x - Result | (2-Byte) Unsigned |
|  | 4 Bytes | 0 | C R - T - | DPT_Value_4_Count | $\begin{array}{r} -2147483648 \\ 2147483647 \\ \hline \end{array}$ | [LF] Function x - Result | (4-Byte) Signed |
|  | 1 Byte | 0 | C R - T - | DPT_Scaling | 0\% - 100\% | [LF] Function x - Result | (1-Byte) Percentage |
|  | 2 Bytes | 0 | C R - T - | DPT_Value_2_Count | -32768-32767 | [LF] Function x - Result | (2-Byte) Signed |
|  | 2 Bytes | 0 | CR - T - | 9.xxx | -671088.64-670433.28 | [LF] Function x - Result | (2-Byte) Float |
| 431 | 1 Byte | I | C-W-- | DPT_SceneControl | 0-63; 128-191 | [Fan Coil] Scenes | $\begin{aligned} & 0-63 \text { (Execute } 1-64) ; 128-191 \\ & \text { (Save } 1-64) \end{aligned}$ |
| 432 | 1 Bit | I | C-W-U | DPT_Switch | 0/1 | [FCx] On/Off | 0 = Off; 1 = On |
| 433 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [FCx] On/Off (Status) | 0 = Off; 1 = On |
| 434 | 1 Bit | I | C-W - U | DPT_Heat_Cool | 0/1 | [FCx] Mode | $0=$ Cool; $1=$ Heat |
| 435 | 1 Bit | 0 | C R - T - | DPT_Heat_Cool | 0/1 | [FCx] Mode (Status) | 0 = Cool; 1 = Heat |
| 436 | 1 Bit | I | C-W-U | DPT_Enable | 0/1 | [FCx] Fan: Manual/Automatic | 0 = Automatic; 1 = Manual |
|  | 1 Bit | I | C-W-U | DPT_Enable | 0/1 | [FCx] Fan: Manual/Automatic | 0 = Manual; 1 = Automatic |
| 437 | 1 Bit | 0 | C R-T- | DPT_Enable | 0/1 | [FCx] Fan: Manual/Automatic (Status) | 0 = Automatic; 1 = Manual |
|  | 1 Bit | 0 | C R-T- | DPT_Enable | 0/1 | [FCx] Fan: Manual/Automatic (Status) | $0=$ Manual; 1 = Automatic |
| 438 | 1 Bit | I | C-W-U | DPT_Step | 0/1 | [FCx] Manual Fan: Step Control | 0 = Down; 1 = Up |
| 439 | 1 Bit | I | C-W-U | DPT_Switch | 0/1 | [FCx] Manual Fan: Speed 0 | $0=$ Off; $1=$ On |
| 440 | 1 Bit | I | C-W-U | DPT_Switch | 0/1 | [FCx] Manual Fan: Speed 1 | $0=$ Off; $1=$ On |
| 441 | 1 Bit | I | C-W-U | DPT_Switch | 0/1 | [FCx] Manual Fan: Speed 2 | $0=$ Off; $1=$ On |
| 442 | 1 Bit | I | C-W-U | DPT_Switch | 0/1 | [FCx] Manual Fan: Speed 3 | 0 = Off; $1=$ On |
| 443 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [FCx] Fan: Speed 0 (Status) | $0=$ Off; $1=$ On |
| 444 | 1 Bit | 0 | CR-T- | DPT_Switch | 0/1 | [FCx] Fan: Speed 1 (Status) | $0=$ Off; $1=$ On |
| 445 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [FCx] Fan: Speed 2 (Status) | $0=$ Off; $1=$ On |
| 446 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [FCx] Fan: Speed 3 (Status) | 0 = Off; 1 = On |
| 447 | 1 Byte | I | C-W-U | DPT_Fan_Stage | 0-255 | [FCx] Manual Fan: Enumeration Control | S0 = 0; S1 = 1; S2 = 2; S3 = 3 |
|  | 1 Byte | I | C-W-U | DPT_Fan_Stage | 0-255 | [FCx] Manual Fan: Enumeration Control | S0 = 0; S1 = 1; S2 = 2 |
|  | 1 Byte | I | C-W-U | DPT_Fan_Stage | 0-255 | [FCx] Manual Fan: Enumeration Control | S0 = 0; S1 = 1 |
| 448 | 1 Byte | 0 | C R - T - | DPT_Fan_Stage | 0-255 | $\begin{aligned} & \text { [FCx] Fan: Speed Enumeration } \\ & \text { (Status) } \end{aligned}$ | $S 0=0 ; S 1=1 ; S 2=2 ; S 3=3$ |


|  | 1 Byte | 0 | C R - T - | DPT_Fan_Stage | 0-255 | [FCx] Fan: Speed Enumeration (Status) | $\mathrm{S} 0=0 ; \mathrm{S} 1=1 ; \mathrm{S} 2=2$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1 Byte | 0 | C R - T - | DPT_Fan_Stage | 0-255 | $\begin{aligned} & \text { [FCx] Fan: Speed Enumeration } \\ & \text { (Status) } \end{aligned}$ | S0 = 0; S1 = 1 |
| 449 | 1 Byte | I | C-W-U | DPT_Scaling | 0\%-100\% | [FCx] Manual Fan: Percentage Control | $\begin{aligned} & S 0=0 \% ; S 1=0,4-33,3 \% ; S 2= \\ & 33,7-66,7 \% ; S 3=67,1-100 \% \end{aligned}$ |
|  | 1 Byte | I | C-W-U | DPT_Scaling | 0\% - 100\% | [FCx] Manual Fan: Percentage Control | $\begin{aligned} & \text { S0 = 0\%; S1 = 1-50\%; S2 = 51- } \\ & 100 \% \end{aligned}$ |
|  | 1 Byte | I | C-W-U | DPT_Scaling | 0\% - 100\% | [FCx] Manual Fan: Percentage Control | S0 = 0\%; S1 = 1-100\% |
| 450 | 1 Byte | 0 | C R - T - | DPT_Scaling | 0\% - 100\% |  | $\begin{aligned} & \mathrm{SO}=0 \% ; \mathrm{S} 1=33,3 \% ; \mathrm{S} 2=66,6 \% ; \\ & \mathrm{S} 3=100 \% \end{aligned}$ |
|  | 1 Byte | 0 | C R - T - | DPT_Scaling | 0\% - 100\% | [FCx] Fan: Speed Percentage (Status) | $\begin{aligned} & S 0=0 \% ; S 1=1-50 \% ; S 2=51- \\ & 100 \% \end{aligned}$ |
|  | 1 Byte | 0 | C R - T - | DPT_Scaling | 0\% - 100\% | [FCx] Fan: Speed Percentage (Status) | S0 = 0\%; S1 = 1-100\% |
| 451 | 1 Byte | I | C-W-U | DPT_Scaling | 0\% - 100\% | [FCx] Cooling Fan: Continuous Control | 0-100\% |
|  | 1 Byte | I | C-W-U | DPT_Scaling | 0\% - 100\% | [FCx] Cooling Valve: PI Control (Continuous) | 0-100\% |
| 452 | 1 Byte | I | C-W-U | DPT_Scaling | 0\% - 100\% | [FCx] Heating Fan: Continuous Control | 0-100\% |
|  | 1 Byte | I | C-W-U | DPT_Scaling | 0\% - 100\% | [FCx] Heating Valve: PI Control (Continuous) | 0-100\% |
| 453 | 1 Bit | I | C-W-U | DPT_OpenClose | 0/1 | [FCx] Cooling Valve: Control Variable (1 bit) | 0 = Open Valve; 1 = Close Valve |
|  | 1 Bit | I | C-W-U | DPT_Switch | 0/1 | [FCx] Cooling Valve: Control Variable (1 bit) | 0 = Close Valve; 1 = Open Valve |
| 454 | 1 Bit | I | C-W-U | DPT_OpenClose | 0/1 | [FCx] Heating Valve: Control Variable (1 bit) | 0 = Open Valve; 1 = Close Valve |
|  | 1 Bit | I | C-W-U | DPT_Switch | 0/1 | [FCx] Heating Valve: Control Variable (1 bit) | 0 = Close Valve; 1 = Open Valve |
| 455 | 1 Bit | 0 | C R - T - | DPT_OpenClose | 0/1 | [FCx] Cooling Valve (Status) | 0 = Open; 1 = Closed |
|  | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [FCx] Cooling Valve (Status) | 0 = Closed; 1 = Open |
|  | 1 Bit | 0 | C R - T - | DPT_OpenClose | 0/1 | [FCx] Valve (Status) | 0 = Open; 1 = Closed |
|  | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [FCx] Valve (Status) | 0 = Closed; 1 = Open |
| 456 | 1 Bit | 0 | C R - T - | DPT_OpenClose | 0/1 | [FCx] Heating Valve (Status) | 0 = Open; 1 = Closed |
|  | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [FCx] Heating Valve (Status) | 0 = Closed; 1 = Open |
| 457 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [FCx] Cooling Valve: Anti-Seize Protection (Status) | $0=$ Not Active; 1 = Active |
|  | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | $\qquad$ | $0=$ Not Active; 1 = Active |
| 458 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [FCx] Heating Valve: Anti-Seize Protection (Status) | $0=$ Not Active; 1 = Active |


| 459 | 1 Byte | 0 | C R - T - | DPT_Scaling | 0\% - 100\% | [FCx] Valve (Status) | 0-100\% |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1 Byte | 0 | C R - T - | DPT_Scaling | 0\% - 100\% | [FCx] Cooling Valve (Status) | 0-100\% |
| 460 | 1 Byte | 0 | C R - T - | DPT_Scaling | 0\% - 100\% | [FCx] Heating Valve (Status) | 0-100\% |
| 461 | 1 Bit | 0 | C R - T - | DPT_Bool | 0/1 | [FCx] Control Value - Error | 0 = No Error; 1 = Error |
| 462 | 2 Bytes | I | C-W-U | DPT_Value_Temp | -273.000 - $670433.28^{\circ}$ | [FCx] Ambient Temperature | Ambient Temperature |
| 463 | 2 Bytes | I | C-W - U | DPT_Value_Temp | -273.000 - 670433.280 | [FCx] Setpoint Temperature | Setpoint Temperature |
| 464 | 2 Bytes | I/O | C R W TU | DPT_TimePeriodMin | 0-65535 | [FCx] Duration of Manual Control | 0 = Endless; 1-1440 min |
|  | 2 Bytes | I/O | C R W T U | DPT_TimePeriodHrs | 0-65535 | [FCx] Duration of Manual Control | 0 = Endless; 1-24 h |
| 465, 537 | 1 Bit | I | C-W - - | DPT_Switch | 0/1 | [HTx] [A] On/Off | $0=$ Off; 1 = On |
| 466, 538 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [HTx] [A] On/Off Status | 0 = Off; 1 = On |
| 467, 539 | 1 Byte | I | C-W - - | DPT_SceneControl | 0-63; 128-191 | [HTx] [A] Scenes | Scene Value |
| 468, 540 | 2 Bytes | I | C-W T U | DPT_Value_Temp | -273.00 ${ }^{\circ}-670433.28^{\circ}$ | [HTx] [A] Temperature Source 1 | External Sensor Temperature |
| 469, 541 | 2 Bytes | I | C-W T U | DPT_Value_Temp | -273.00 ${ }^{\circ}-670433.28^{\circ}$ | [HTx] [A] Temperature Source 2 | External Sensor Temperature |
| 470, 542 | 2 Bytes | 0 | C R - T - | DPT_Value_Temp | -273.00 ${ }^{\circ}-670433.28^{\circ}$ | [HTx] [A] Room Temperature | Current Temperature |
| 471, 543 | 1 Bit | I/O | C R W - - | DPT_Heat_Cool | 0/1 | [HTx] [A] System Mode | 0 = Cooling; 1 = Heating |
| 472, 544 | 1 Bit | I/O | C R W - - | DPT_Heat_Cool | 0/1 | [HTx] [A] User Mode | 0 = Cooling; 1 = Heating |
| 473, 545 | 1 Bit | I/O | C R W - - | DPT_Switch | 0/1 | [HTx] [A] Force System Mode | 0 = User Mode / Auto Change; 1 = System Mode |
| 474, 546 | 1 Bit | 0 | C R - T - | DPT_Heat_Cool | 0/1 | [HTx] [A] Mode Status | 0 = Cooling; 1 = Heating |
| 475, 547 | 1 Byte | 0 | C R-T- | DPT_HVACContrMode | $\begin{gathered} \hline 0=\text { Auto } \\ 1=\text { Heat } \\ 3=\text { Cool } \\ 9=\text { Fan } \\ 14=\text { Dry } \\ \hline \end{gathered}$ | [HTx] [A] Split: Mode | $1=$ Heat; $3=$ Cooling; $9=$ Fan; $14=$ Dry |
| 476,548 | 1 Byte | I | C-W T U | DPT_Scaling | 0\%-100\% | [HTx] [A] Fan Speed | 0\%-100\% |
| 477, 549 | 1 Bit | I | C-W T U | DPT_Enable | 0/1 | [HTx] [A] Fan: Manual/Automatic | 0 = Manual; 1 = Automatic |
|  | 1 Bit | I | C-W T U | DPT_Enable | 0/1 | [HTx] [A] Fan: Manual/Automatic | 0 = Automatic; 1 = Manual |
| 478, 550 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [HTx] [A] On/Off Fancoil | 0 = Off; 1 = On |
| 479, 551 | 1 Bit | I | C-W-- | DPT_Reset | 0/1 | [HTx] [B] User Comfort Setpoint Reset | 0 = Nothing; 1 = Reset |
| 480, 552 | 2 Bytes | I | C-W T U | DPT_Value_Temp | -273.000 - $670433.28^{\circ}$ | [HTx] [B] User Setpoint Control | [-20 $\left.{ }^{\circ} \mathrm{C}, 100^{\circ} \mathrm{C}\right]$ |
|  | 2 Bytes | I | C-W T U | DPT_Value_Tempd | $\begin{gathered} \hline-671088.640- \\ 670433.28^{\circ} \\ \hline \end{gathered}$ | [HTx] [B] User Setpoint Offset | [-15 $\left.{ }^{\circ} \mathrm{C}, 15^{\circ} \mathrm{C}\right]$ |
| 481, 553 | 1 Bit | I | C-W - - | DPT_Step | 0/1 | [HTx] [B] Step User Setpoint | 0 = Decrease; 1 = Increase |
| 482, 554 | 2 Bytes | I/O | C R W T U | DPT_Value_Temp | -273.000 - 670433.280 | $[\mathrm{HTx}][\mathrm{B}]$ Comfort Setpoint (Cooling) | [-20 $\left.{ }^{\circ} \mathrm{C}, 100^{\circ} \mathrm{C}\right]$ |
|  | 2 Bytes | I/O | C R W T U | DPT_Value_Temp | -273.000 - 670433.280 | [HTx] [B] Comfort Setpoint | $\left[-20^{\circ} \mathrm{C}, 100^{\circ} \mathrm{C}\right]$ |
| 483, 555 | 2 Bytes | I/O | C R W T U | DPT_Value_Temp | -273.000 - 670433.280 | $[\mathrm{HTx}][\mathrm{B}]$ Standby Setpoint (Cooling) | $\left[-20^{\circ} \mathrm{C}, 100^{\circ} \mathrm{C}\right]$ |
| 484, 556 | 2 Bytes | I/O | C R W T U | DPT_Value_Temp | -273.000 - 670433.280 | [HTx] [B] Economy Setpoint (Cooling) | $\left[-20^{\circ} \mathrm{C}, 100^{\circ} \mathrm{C}\right]$ |
| 485, 557 | 2 Bytes | I/O | C R W T U | DPT_Value_Temp | -273.000 - 670433.280 | $[\mathrm{HTx}][\mathrm{B}]$ Protection Setpoint (Cooling) | $\left[-20^{\circ} \mathrm{C}, 100^{\circ} \mathrm{C}\right]$ |


| 486, 558 | 2 Bytes | I/O | C R W T U | DPT_Value_Temp | -273.000 - 670433.280 | $[\mathrm{HTx}][\mathrm{B}]$ Comfort Setpoint (Heating) | [-20 $\left.{ }^{\circ} \mathrm{C}, 100^{\circ} \mathrm{C}\right]$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 487, 559 | 2 Bytes | I/O | C R W T U | DPT_Value_Temp | -273.000 - 670433.280 | $\begin{aligned} & {[\mathrm{HTx}][\mathrm{B}] \text { Standby Setpoint }} \\ & \text { (Heating) } \end{aligned}$ | $\left[-20^{\circ} \mathrm{C}, 100^{\circ} \mathrm{C}\right]$ |
| 488, 560 | 2 Bytes | I/O | C R W T U | DPT_Value_Temp | -273.000 - 670433.280 | $\underset{\text { (Heating) }}{[\mathrm{HTx}][\mathrm{B}] \text { Economy Setpoint }}$ | $\left[-20^{\circ} \mathrm{C}, 100^{\circ} \mathrm{C}\right]$ |
| 489, 561 | 2 Bytes | I/O | C R W T U | DPT_Value_Temp | -273.000 - 670433.280 | $\underset{(H e a t i n g)}{[\mathrm{HTx}][B] \text { Protection Setpoint }}$ | [-20 $\left.{ }^{\circ} \mathrm{C}, 100^{\circ} \mathrm{C}\right]$ |
| 490, 562 | 2 Bytes | 0 | C R - T - | DPT_Value_Temp | -273.00 $-670433.28^{\circ}$ | [HTx] [B] Real Setpoint Status | [-20 $\left.{ }^{\circ} \mathrm{C}, 100^{\circ} \mathrm{C}\right]$ |
| 491, 563 | 2 Bytes | 0 | C R - T - | DPT_Value_Temp | -273.00 ${ }^{\circ}-670433.28^{\circ}$ | [HTx] [B] User Setpoint Status | [-20 $\left.{ }^{\circ} \mathrm{C}, 100^{\circ} \mathrm{C}\right]$ |
|  | 2 Bytes | 0 | C R - T - | DPT_Value_Tempd | $\begin{gathered} -671088.640 \\ 670433.28^{\circ} \\ \hline \end{gathered}$ | [HTx] [B] User Setpoint Offset Status | [-15 $\left.{ }^{\circ} \mathrm{C}, 15^{\circ} \mathrm{C}\right]$ |
| 492, 564 | 2 Bytes | 0 | C R - T - | DPT_Value_Temp | -273.000 - 670433.280 | [HTx] [B] Setpoint to Split | [-20 $\left.{ }^{\circ} \mathrm{C}, 100^{\circ} \mathrm{C}\right]$ |
| 493, 565 | 2 Bytes | I/O | C R W T U | DPT_TimePeriodSec | 0-65535 | [HTx] [C] Transition Time: Comfort to Default Mode | Seconds (0 = Disabled) |
|  | 2 Bytes | I/O | C R W T U | DPT_TimePeriodMin | 0-65535 | [HTx] [C] Transition Time: Comfort to Default Mode | Minutes (0 = Disabled) |
|  | 2 Bytes | I/O | C R W T U | DPT_TimePeriodHrs | 0-65535 | [HTx] [C] Transition Time: Comfort to Default Mode | Hours (0 = Disabled) |
| 494, 566 | 2 Bytes | I/O | C R W T U | DPT_TimePeriodSec | 0-65535 | [HTx] [C] Transition Time: Standby to Economy | Seconds (0 = Disabled) |
|  | 2 Bytes | I/O | C R W T U | DPT_TimePeriodMin | 0-65535 | $\begin{aligned} & \text { [HTx] [C] Transition Time: Standby } \\ & \text { to Economy } \\ & \hline \end{aligned}$ | Minutes (0 = Disabled) |
|  | 2 Bytes | I/O | C R W T U | DPT_TimePeriodHrs | 0-65535 | [HTx] [C] Transition Time: Standby to Economy | Hours (0 = Disabled) |
| 495, 567 | 2 Bytes | I/O | C R W T U | DPT_TimePeriodSec | 0-65535 | [HTx] [C] Comfort Setpoint Reset Time | Seconds (0 = Disabled) |
|  | 2 Bytes | I/O | C R W T U | DPT_TimePeriodMin | 0-65535 | [HTx] [C] Comfort Setpoint Reset Time | Minutes (0 = Disabled) |
|  | 2 Bytes | I/O | C R W T U | DPT_TimePeriodHrs | 0-65535 | [HTx] [C] Comfort Setpoint Reset Time | Hours (0 = Disabled) |
| 496,568 | 1 Bit | I/O | C R W - - | DPT_Occupancy | 0/1 | [HTx] [C] Presence Detector (Input) | $0=$ Not Occupied; 1 = Occupied |
| 497, 569 | 1 Bit | I/O | C R W -- | DPT_Enable | 0/1 | [ HTx ] [C] Lock Presence Detection | 0 = Unlocked; 1 = Locked |
|  | 1 Bit | I/O | C R W - - | DPT_Enable | 0/1 | [HTx] [C] Lock Presence Detection | 0 = Locked; 1 = Unlocked |
| 498, 570 | 1 Bit | I/O | C R W - - | DPT_Bool | 0/1 | [HTx] [C] Sold/Unsold Room (Input) | 0 = Unsold; 1 = Sold |
| 499, 571 | 1 Byte | I | C-W-- | DPT_HVACMode | $\begin{gathered} \hline 1=\text { Comfort } \\ 2=\text { Standby } \\ 3=\text { Economy } \\ \text { 4 }=\text { Building } \\ \text { Protection } \\ \hline \end{gathered}$ | [HTx] [D] Special Mode | 1-byte HVAC Mode |
| 500, 572 | 1 Bit | I | C-W - - | DPT_Ack | 0/1 | [HTx] [D] Special Mode: Comfort | 0 = Nothing; 1 = Trigger |
|  | 1 Bit | I | C-W -- | DPT_Switch | 0/1 | [HTx] [D] Special Mode: Comfort | $0=$ Off; 1 = On |
| 501, 573 | 1 Bit | I | C-W - - | DPT_Ack | 0/1 | [HTx] [D] Special Mode: Standby | 0 = Nothing; 1 = Trigger |
|  | 1 Bit | I | C-W - - | DPT_Switch | 0/1 | [HTx] [D] Special Mode: Standby | 0 = Off; 1 = On |


| 502, 574 | 1 Bit | I | C - W - - | DPT_Ack | 0/1 | [HTx] [D] Special Mode: Economy | $0=$ Nothing; 1 = Trigger |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1 Bit | I | C-W -- | DPT_Switch | 0/1 | [HTx] [D] Special Mode: Economy | 0 = Off; 1 = On |
| 503, 575 | 1 Bit | I | C - W - - | DPT_Ack | 0/1 | [HTx] [D] Special Mode: Protection | $0=$ Nothing; $1=$ Trigger |
|  | 1 Bit | I | C-W - - | DPT_Switch | 0/1 | [HTx] [D] Special Mode: Protection | 0 = Off; 1 = On |
| 504, 576 | 1 Byte | 0 | C R-T- | DPT_HVACMode | $\begin{gathered} \hline 1=\text { Comfort } \\ 2=\text { Standby } \\ 3=\text { Economy } \\ \text { 4 }=\text { Building } \\ \text { Protection } \\ \hline \end{gathered}$ | [HTx] [D] Special Mode Status | 1-byte HVAC Mode |
| 505, 577 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [HTx] [D] Comfort Mode Status | 0 = Off; 1 = On |
| 506, 578 | 1 Bit | I | C - W - - | DPT_Window_Door | 0/1 | [HTx] [D] Window Status 1 (Input) | 0 = Closed; 1 = Open |
|  | 1 Bit | I | C-W - - | DPT_Window_Door | 0/1 | [HTx] [D] Window Status 1 (Input) | $0=$ Open; 1 = Closed |
| 507,579 | 1 Bit | I | C - W - - | DPT_Window_Door | 0/1 | [HTx] [D] Window Status 2 (Input) | 0 = Closed; 1 = Open |
|  | 1 Bit | I | C - W - - | DPT_Window_Door | 0/1 | [HTx] [D] Window Status 2 (Input) | 0 = Open; 1 = Closed |
| 508, 580 | 1 Bit | I | C - W - - | DPT_Window_Door | 0/1 | [HTx] [D] Window Status 3 (Input) | 0 = Closed; 1 = Open |
|  | 1 Bit | I | C-W -- | DPT_Window_Door | 0/1 | [HTx] [D] Window Status 3 (Input) | $0=$ Open; 1 = Closed |
| 509, 581 | 1 Bit | I | C - W - - | DPT_Window_Door | 0/1 | [HTx] [D] Window Status 4 (Input) | 0 = Closed; 1 = Open |
|  | 1 Bit | I | C-W - - | DPT_Window_Door | 0/1 | [HTx] [D] Window Status 4 (Input) | 0 = Open; 1 = Closed |
| 510, 582 | 1 Bit | I/O | C R W - - | DPT_Enable | 0/1 | [HTx] [D] Enable Window Status | 0 = Disabled; 1 = Enabled |
| 511, 583 | 1 Bit | I | C - W - - | DPT_Window_Door | 0/1 | [HTx] [D] Door Status 1 (Input) | 0 = Closed; 1 = Open |
|  | 1 Bit | I | C-W - - | DPT_Window_Door | 0/1 | [HTx] [D] Door Status 1 (Input) | 0 = Open; 1 = Closed |
| 512, 584 | 1 Bit | I | C-W - - | DPT_Window_Door | 0/1 | [HTx] [D] Door Status 2 (Input) | 0 = Closed; 1 = Open |
|  | 1 Bit | I | C - W - - | DPT_Window_Door | 0/1 | [HTx] [D] Door Status 2 (Input) | 0 = Open; 1 = Closed |
| 513, 585 | 1 Bit | I/O | C R W -- | DPT_Enable | 0/1 | [HTx] [D] Enable Door Status | 0 = Disabled; 1 = Enabled |
| 514, 586 | 1 Bit | I/O | C R W - - | DPT_Enable | 0/1 | [HTx] [D] Thermostat Lock | 0 = Locked; 1 = Unlocked |
|  | 1 Bit | I/O | C R W - - | DPT_Enable | 0/1 | [HTx] [D] Thermostat Lock | 0 = Unlocked; 1 = Locked |
| 515, 587 | 2 Bytes | I/O | C R W T U | DPT_Value_Temp | -273.000 - $670433.28^{\circ}$ | [HTx] [D] Comfort Lower Limit | $\left[-20^{\circ} \mathrm{C}, 100^{\circ} \mathrm{C}\right]$ |
| 516, 588 | 2 Bytes | I/O | C R W T U | DPT_Value_Temp | -273.000 - 670433.280 | [HTx] [D] Comfort Upper Limit | [-20 $\left.{ }^{\circ} \mathrm{C}, 100^{\circ} \mathrm{C}\right]$ |
| 517, 589 | 1 Bit | I/O | C R W - - | DPT_Switch | 0/1 | [HTx] [D] Hidden Offset On/Off | 0 = Off; 1 = On |
| 518, 590 | 2 Bytes | I/O | C R W T U | DPT_Value_Tempd | $\begin{gathered} -671088.64^{\circ}- \\ 670433.28^{\circ} \\ \hline \end{gathered}$ | [HTx] [D] Hidden Offset Value | $\left[-20^{\circ} \mathrm{C}, 100^{\circ} \mathrm{C}\right]$ |
| 519, 591 | 1 Bit | 0 | C R - T - | DPT_Bool | 0/1 | [HTx] [D] Eco Mode Notification | 0 = Out of Eco Range; 1 = Setpoint in Eco Range |
| 520, 592 | 1 Byte | 0 | C R - T - | DPT_Scaling | 0\%-100\% | [HTx] [D] Eco Mode Ratio | Percentage of Time Working in Eco Range |
| 521, 593 | 2 Bytes | I/O | C R W T U | DPT_Value_Temp | -273.000 - 670433.280 | [HTx] [D] Eco Mode: Lower Limit (Cooling) | Lower Value for the Ecological Range |
| 522,594 | 2 Bytes | I/O | C R W T U | DPT_Value_Temp | -273.000 - 670433.280 | [HTx] [D] Eco Mode: Upper Limit (Heating) | Upper Value for the Ecological Range |
| 523, 595 | 2 Bytes | I | C - W - - | DPT_Value_Humidity | -12\% - 12\% | [HTx] [F] Current Humidity | Humidity Sensor Value |
| 524, 596 | 2 Bytes | I/O | C R W T U | DPT_Value_Humidity | -12\%-12\% | [HTx] [F] High Humidity Alarm Threshold | Value of High Humidity Alarm Threshold |
| 525, 597 | 1 Bit | I/O | C R W T U | DPT_Enable | 0/1 | [HTx] [F] Dehumidification Control | 0 = Disabled; 1 = Enabled |


| 526,598 | 1 Bit | 0 | C R - T - | DPT_Bool | 0/1 | [HTx] [F] Dehumidification Status | 0 = No Dehumidifying; 1 = Dehumidifying |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 527, 599 | 1 Bit | 0 | C R - T - | DPT_Alarm | 0/1 | [HTx] [F] High Humidity | 0 = No Alarm; 1 = Alarm |
| 528,600 | 1 Bit | I/O | C R W T U | DPT_Enable | 0/1 | [HTx] [F] Enable Apparent Temperature | 0 = Room Temperature; 1 = Apparent Temperature |
| 529, 601 | 1 Byte | 0 | C R - T - | DPT_Scaling | 0\% - 100\% | [HTx] [Cooling] Control Variable | PI Control (Continuous) |
| 530,602 | 1 Byte | 0 | C R - T - | DPT_Scaling | 0\% - 100\% | [HTx] [Heating] Control Variable | PI Control (Continuous) |
| 531,603 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [HTx] [Cooling] Control Variable | 2-Point Control |
|  | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [HTx] [Cooling] Control Variable | PI Control (PWM) |
| 532,604 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [HTx] [Heating] Control Variable | 2-Point Control |
|  | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [HTx] [Heating] Control Variable | PI Control (PWM) |
| 533, 605 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [HTx] [Cooling] Additional Cool | Temp >= (Setpoint+Band) => "1" |
| 534,606 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [HTx] [Heating] Additional Heat | Temp <= (Setpoint-Band) => "1" |
| 535,607 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [HTx] [Cooling] PI State | $\begin{aligned} & 0=\text { PI Signal } 0 \% ; 1=\text { PI Signal } \\ & \text { Greater than } 0 \% \end{aligned}$ |
| 536,608 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [HTx] [Heating] PI State | $0 \text { = PI Signal 0\%; } 1=\text { PI Signal }$ Greater than 0\% |
| 609 | 1 Bit | I | C-W - - | DPT_Trigger | 0/1 | [MLx] Trigger | Trigger the Master Light Function |
|  | 1 Bit | I | C-W-- | DPT_Ack | 0/1 | [MLx] Trigger | $0=$ Nothing; 1 = Trigger the Master Light Function |
|  | 1 Bit | I | C-W-- | DPT_Ack | 0/1 | [MLx] Trigger | 1 = Nothing; $0=$ Trigger the Master Light Function |
| 610, 611, 612, 613, 614, $615,616,617,618,619$, $620,621,622,623,624$, $625,626,627,628,629$, $630,631,632,633,634$, $635,636,637,638,639$ | 1 Bit | I | C-W-- | DPT_Switch | 0/1 | [MLx] Status Object x | Binary Status |
| 640 | 1 Bit | 0 | C R - T - | DPT_Switch | 0/1 | [MLx] General Status | Binary Status |
| 641 | 1 Bit |  | C - - ${ }^{\text {- }}$ | DPT_Switch | 0/1 | [MLx] General Switch Off: Binary Object | Switch Off Sending |
| 642 | 1 Byte |  | C - - T - | DPT_Scaling | 0\% - 100\% | [MLx] General Switch Off: Scaling | 0-100\% |
| 643 | 1 Byte |  | C - - T- | DPT_SceneControl | 0-63; 128-191 | [MLx] General Switch Off: Scene | Scene Sending |
| 644 | 1 Byte |  | C-- T- | DPT_HVACMode | $\begin{gathered} 1=\text { Comfort } \\ 2=\text { Standby } \\ 3=\text { Economy } \\ 4=\text { Building } \\ \text { Protection } \\ \hline \end{gathered}$ | [MLx] General Switch Off: HVAC mode | Auto, Comfort, Standby, Economy, Building Protection |
| 645 | 1 Bit |  | C - - ${ }^{\text {- }}$ | DPT_Switch | 0/1 | [MLx] Courtesy Switch On: Binary Object | Switch On Sending |
| 646 | 1 Byte |  | C - - T - | DPT_Scaling | 0\%-100\% | [MLx] Courtesy Switch On: Scaling | 0-100\% |
| 647 | 1 Byte |  | C - - T- | DPT_SceneNumber | 0-63 | [MLx] Courtesy Switch On: Scene | Scene Sending |
| 648 | 1 Byte |  | C-- T- | DPT_HVACMode | $\begin{aligned} & \hline 1=\text { Comfort } \\ & 2=\text { Standby } \\ & \hline \end{aligned}$ | [MLx] Courtesy Switch On: HVAC mode | Auto, Comfort, Standby, Economy, Building Protection |


|  |  |  |  |  | $3=$ Economy <br> $4=$ Building <br> Protection |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| 649 | 1 Bit |  | C $--\mathrm{T}-$ | DPT_Trigger | $0 / 1$ | [Heartbeat] Object to Send ' 1 ' | Sending of '1' Periodically |
| 650 | 1 Bit |  | C - T - | DPT_Trigger | $0 / 1$ | [Heartbeat] Device Recovery | Send 0 |
| 651 | 1 Bit |  | C - T - | DPT_Trigger | $0 / 1$ | [Heartbeat] Device Recovery | Send 1 |

# Join and send us your inquiries about Zennio devices: https://support.zennio.com 

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[^0]:    ${ }^{1}$ The default values of each parameter will be highlighted in this document, as follows: [default / rest of options].

